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Step 11 of 20 In the mechanism the link 3 (seat) and link 6 (arms) are ternary links because these are connected to the others by 3 pin joints. The link 3 is coupled to the front leg, back link 5 and to the link 4. The link 6 is connected to the link 2, link 1 and back link 5.

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Library of Congress Cataloging-in-Publication Data Norton, Robert L. Design of machinery: an introduction to the synthesis and analysis of mechanisms and machines / Robert L. Norton - 2nd ed. p. cm. -- {McGraw-Hill series in mechanical engineering)

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